

Release Notes FIZC Firmware Release 1.3.1

1. Introduction

This document contains all information you need for updating your Newton FIZC dongle to firmware version 1.3.1. The software and USB to CAN dongle is compatible with Windows (7, 8, 8.1 and 10) or macOS (tested with v10.14 Mojave, others might work).

IMPORTANT!: Update all of the devices (Controller, Head, camera/lens dongles) to the latest firmware version to ensure compatibility.

2. Changelog

This is a bugfix release that fixes one bug with zoom speed on Teradek RT / RTmotion

Compared to the previous major release (1.2.0) the following has been changed:

- Support for new improved communication protocol
- Implemented a fix for certain versions of the Teradek RT / RTmotion system where motors would "jump" at end of range

3. Update Instruction

3.1. Install USB to CAN interface driver

This step is required on Windows computers the first time you want to utilize the IA USB to CAN interface.

1. Run the file **dpinst_32.exe** (for 32-bit Windows) or **dpinst_64.exe** (for 64-bit Windows) from the **windows-drivers** folder
2. Follow the on-screen instructions to install the driver
3. Connect the USB-CAN interface to the computer
4. The USB to CAN interface should now be visible in the device manager under the "Ports" section

3.2. Upgrade firmware

1. Connect CAN dongle via USB to the computer
2. Connect CAN connector of CAN dongle to one of the CAN ports on the Newton device
3. Run **firmware_gui.exe** from the Windows folder or **firmware_gui.app** from OSX folder
4. Follow the instructions in the installation wizard. From the **firmware** folder, select the correct file for the product you are updating
5. Press update